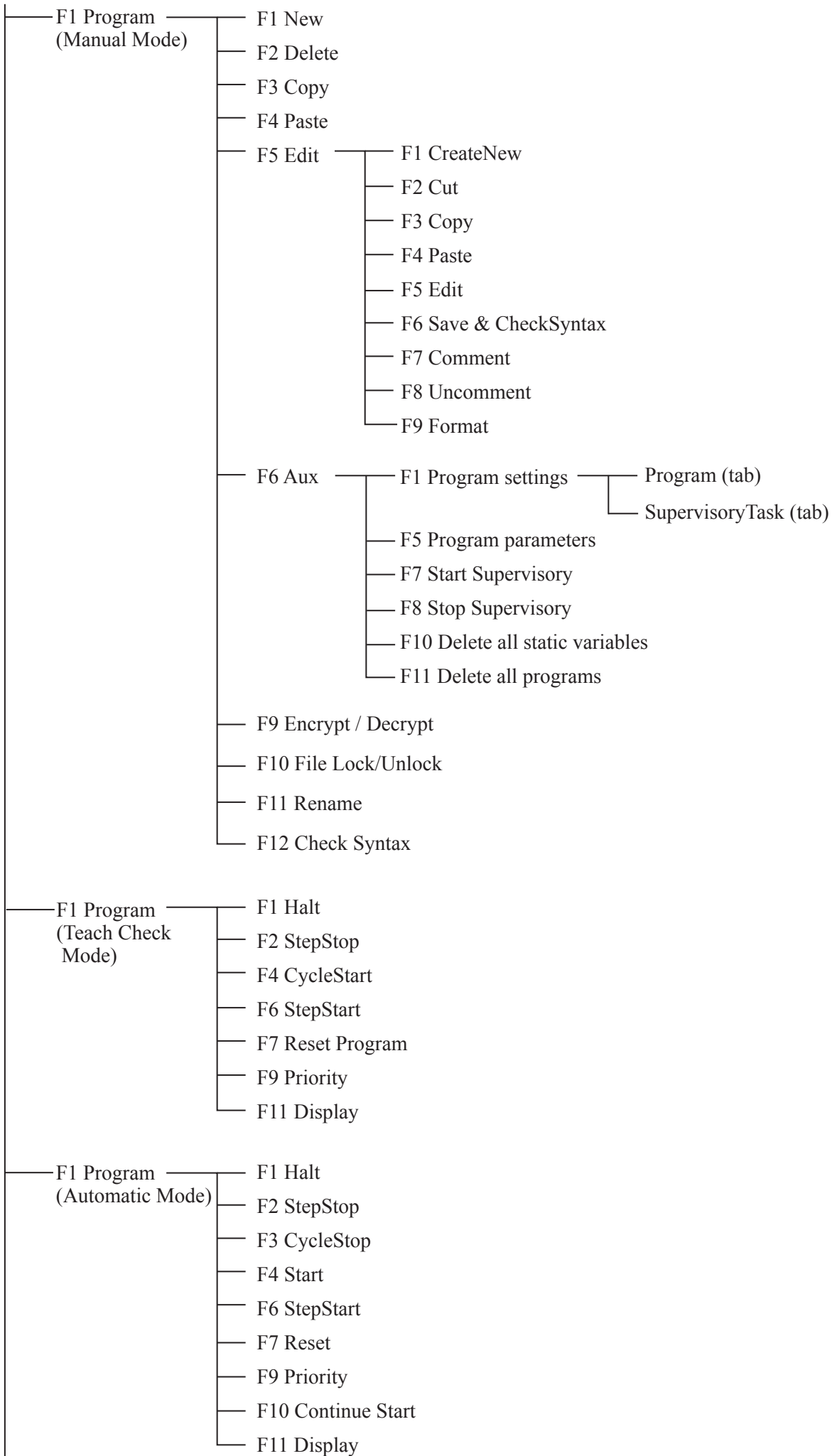


Basic Screen



F2 Arm

F1 PositionDisplayStyle

F2 Force Control

F3 Servo State

Monitor (tab)

CtrlLog (tab)

ServoLog (tab)

Estimate (tab)

F6 Setting

F6 Setting

F4 Variable

F1 Prev

F2 Next

F3 Jump To

F4 MoveTo (for P, J, and T only)

F5 Edit

F6 Get Position (for P, J, and T only)

F8 Copy

F9 Paste

F10 Switch Display

F11 Robot

F12 Aux

F1 Number of Variables

F2 Delete all variables

F6 Aux

F1 Config

F2 Collision/Interference

F1 Collision Detection

F2 Virtual Fence

F3 Tool

F4 EasyEdit

F4 Work

F4 EasyEdit

F5 Area

F4 EasyEdit

F6 PathPoint

F7 Detail

F7 Display Settings

F8 Direct Teach (for 4-axis robot only)

F9 Z Balance (for 4-axis robot only)

F10 Base

F4 EasyEdit

F11 Exclusive Control

F12 Maintenance

F1 Brake

F2 Encoder

F1 Encoder Info

F7 Reset encoder

F8 Encoder ID

F9 Encoder reference

F3 Driver Unit

F7 CALSET (for Maintainer level only)

F1 CALSET

F2 Recover CALSET data

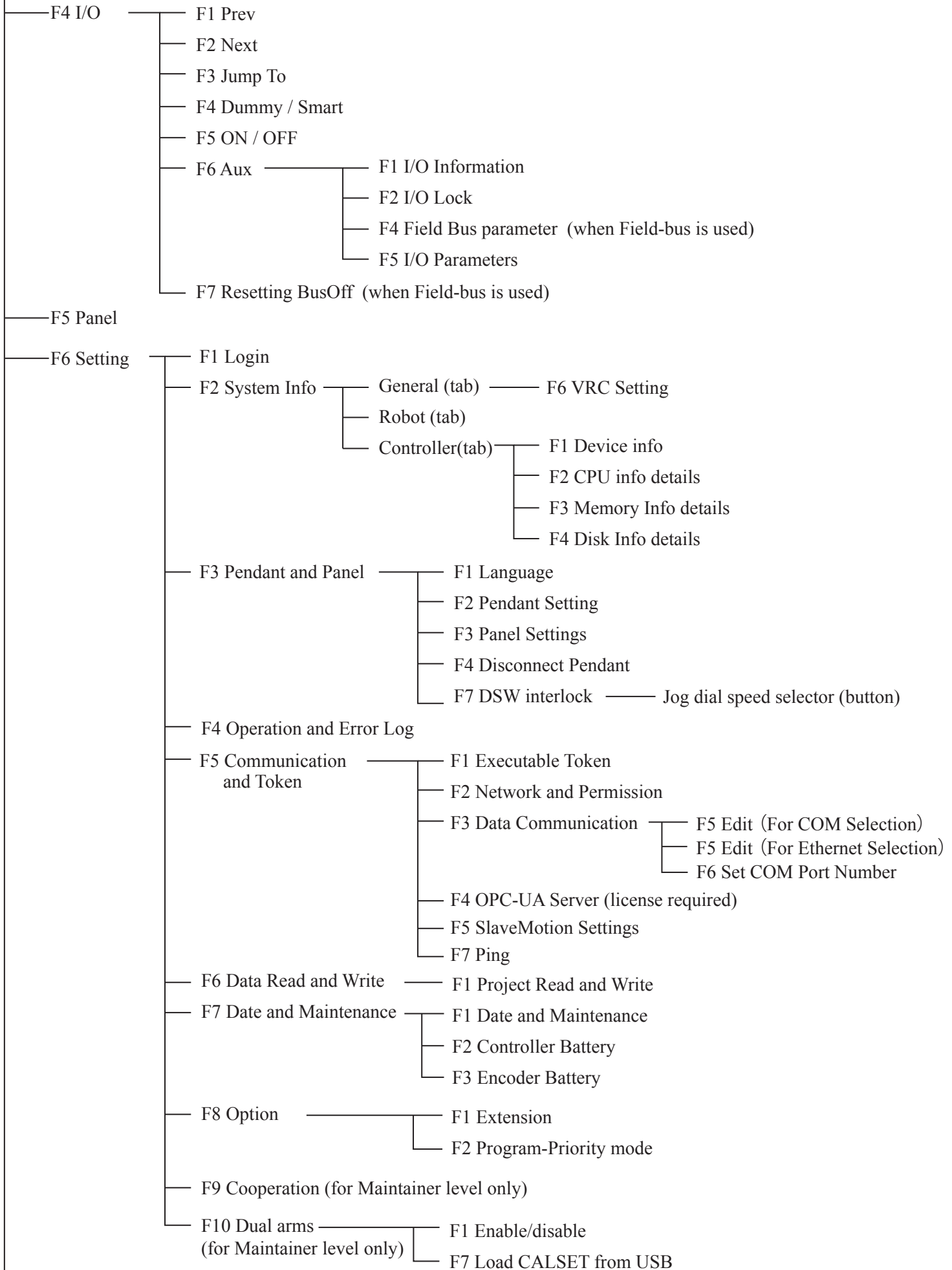
F3 Input Number

F8 Motion Space

F9 Motion range of R axis (for XR series only)

F12 Service (for Maintainer level only) — F1 Acceleration Limit

F3 Variable — Same as F4 Variable under F2 Arm



③

